

Listing of All Claims Including Current Amendments

1.-33. (Cancelled)

34. (Currently amended) Method of servicing outer components of a wind turbine with a work platform, said method comprising:

positioning the work platform at the wind turbine tower;

connecting the work platform to an upper part of the wind turbine with at least one cable;

raising the work platform with the cable and a cable winding means winder to a position of use; and

holding the work platform to a side of the wind turbine tower by directly gripping the tower with a holding means holder comprised in the work platform; and

moving the work platform horizontally by extracting or retracting a horizontal forcer of the work platform.

35. (Withdrawn) Method according to claim 34, wherein said holding is established with at least two sets of suction or vacuum cups.

36. (Withdrawn – Currently amended) Method according to claim 34, wherein said holding is established with at least two sets of electromagnetic means electromagnets.

37. (Currently amended) Method according to claim 34, wherein said holding is established with retaining means a retainer surrounding said wind turbine tower.

38. (Withdrawn – Currently amended) Method according to claim 34, wherein said holding is enhanced by positioning suction or vacuum cups or electro-magnetic means electromagnets on the ends of holding arms, said arms gripping around the exterior of the wind turbine tower.

39. (Cancelled).

40. (Currently amended) Method according to claim [[39]] 34, wherein the extracting or retracting is established telescopically by a number of arm sections in said horizontal forcing means forcer.

41. (Currently amended) Method according to claim 34, wherein cable guiding means guide angles the cable outwards in relation to the wind turbine tower from the starting point of the cable.

42. (Previously presented) Method according to claim 34, wherein said work platform is moved up or down by following and rolling with steering wheels of the platform on a surface of the wind turbine tower.

43. (Currently amended) Work platform for servicing outer components of a wind turbine, said platform comprising:

at least one cable connecting the work platform with an upper part of the wind turbine;

a cable winding means winder winding said at least one cable; and

a gripping means gripper for directly holding the work platform to the tower, said gripper comprising at least one holding arm including a base arm section, an inner arm section, and an outer arm section;

wherein said inner arm section and said outer arm section are pivotally connected and controlled by a holding arm actuator in at least one direction.

44. (Previously presented) Work platform according to claim 43, wherein said at least one cable comprises a set of outer cables, said set including a main cable and one or more additional cables.

45. (Currently amended) Work platform according to claim [[43]] 44, wherein said at least one cable further comprises an inner cable or cables.

46. (Currently amended) Work platform according to claim [[44]] 45, wherein said inner and outer cables are fixed to an underside of a wind turbine nacelle at an inner and outer anchorage point in a direction from the tower or to anchorage points inside the nacelle.

47. (Withdrawn – Currently amended) Work platform according to claim 43, wherein said gripping means gripper comprises at least two sets of suction or vacuum cups.

48. (Withdrawn – Currently amended) Work platform according to claim 43, wherein said gripping means gripper comprises at least two sets of electromagnetic means electromagnets.

49. (Currently amended) Work platform according to claim 43, wherein said gripping means gripper comprises retaining means a retainer surrounding the wind turbine tower.

50. (Withdrawn – Currently amended) Work platform according to claim 47, wherein said gripping means gripper comprises at least two sets of suction or vacuum cups or electromagnetic means electromagnets where such are flexibly mounted to an end of [[a]] said holding arm.

51-52. (Cancelled).

53. (Currently amended) Work platform according to claim 43, wherein said gripping means gripper comprises one or more steering wheels.

54. (Previously presented) Work platform according to claim 43, wherein guard rails and a foundation define a work area of said platform.

55. (Currently amended) Work platform according to claim 54, wherein said ~~gripping means gripper~~ and the foundation are connected through a horizontal forcing means forcer.

56. (Currently amended) Work platform according to claim 55, wherein said horizontal ~~forcing means forcer~~ includes a number of horizontal forcing arms.

57. (Currently amended) Work platform according to claim 56, wherein said horizontal forcing arms are integrated into each other as part of a telescopic forcing means forcer.

58. (Previously presented) Work platform according to claim 43, wherein a side or sides of said platform includes one or more indentations for receiving and docking one or more wind turbine blades.

59. (Currently amended) Work platform according to claim 58, wherein said platform includes a retainer retaining means for retaining the wind turbine blade in one of said indentations.

60. (Currently amended) Work platform according to claim 59, wherein said retainer retaining means includes one or more suction or vacuum cups positioned on one or more rods as a base part for the retainer retaining means.

61. (Currently amended) Work platform according to claim 43, wherein said at least one cable is controlled by a cable guiding means guide.

62. (Currently amended) Work platform according to claim 61, wherein a position of said cable guiding means guide controls an angling of the at least one cable.

63. (Currently amended) Work platform according to claim 61, wherein said cable guiding means guide angles the cable outwards in relation to the wind turbine tower from an anchorage point of the cable.

64. (Currently amended) Work platform according to claim 43, wherein said platform includes a control means mechanism for controlling said holding arm actuator actuating means, a horizontal forcing means forcer, one or more suction or vacuum pumps and/or a cable winding means winder.

65. (Currently amended) Work platform according to claim 64, wherein said control means mechanism is connected wired or wirelessly to and controlled by at least one remote control.

66. (Currently amended) Work platform according to claim 64, wherein said control means mechanism, said arm actuator, said horizontal forcer, said one or more suction or vacuum pumps and/or said cable winder and auxiliary devices are controlled with more than one remote control, said controls working in a master and slave configuration.